

Patent Attorney's Docket No. <u>010063-020</u>

July-99 1-19-99 1-19-99

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re Patent Application of)	
Genov, et al.)	Group Art Unit: 2837
Application No.: 09/079,850)	Examiner: B. Sircus
Filed: May 15, 1998)	
For: ROBOT HAVING MULTIPLE)	HEGEW-
DEGREES OF FREEDOM)	UEC 2 9 199h
AMENDMENT		GROUP 2100

Assistant Commissioner for Patents Washington, D.C. 20231

Sir:

In response to the Office Action dated August 19, 1998, please amend the aboveidentified application as follows:

In the Claims:

SUP V2

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1. (Twice Amended) A robotic arm structure providing θ motion and R motion, comprising:

at lea

at least two links, each having a proximalmost end portion and a distalmost end portion, with the θ motion being about a primary axis at the proximal end portion of a

proximalmost of the links and the R protion proceeding radially from the primary axis

[whorehy the distal and portion of a distalment of the links can be mayed radially in a

[whereby the distal end portion of a distalmost of the links can be moved radially in a

7 straight line,];

an end effector attached to the distalmost link and being rotatable about an

9 end effector axis

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